

Lawrence Livermore National Laboratory

# Satellite Track Extraction from STARE Images

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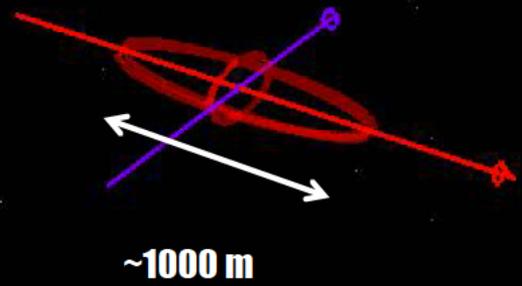
LLNL-PRES-637814

# Agenda

- STARE Motivation and Concept
- STARE Track Extraction Algorithm
  - Image Pre-Processing
  - Curved Track Fitting
  - Endpoint Determination
- Conclusion



# UNCERTAINTY IN THE ORBIT OF EARTH SATELLITES – WHERE WE ARE NOW



# UNCERTAINTY IN THE ORBIT OF EARTH SATELLITES – WHERE WE WOULD LIKE TO BE



~100 m



# Conjunction Threshold Uncertainty and False Alarm Rate

Iridium constellation conjunction rate (Apr-May 2010):

Threshold	Per Month	Per Day	Relative Rate Reduction
10000m	36574	1219	
1000m	354	11.8	99.03%
100m	3	0.1	99.99%

**By the time  $\sigma < 100\text{m}$ , the false alarm rate has dropped by 99.99%**



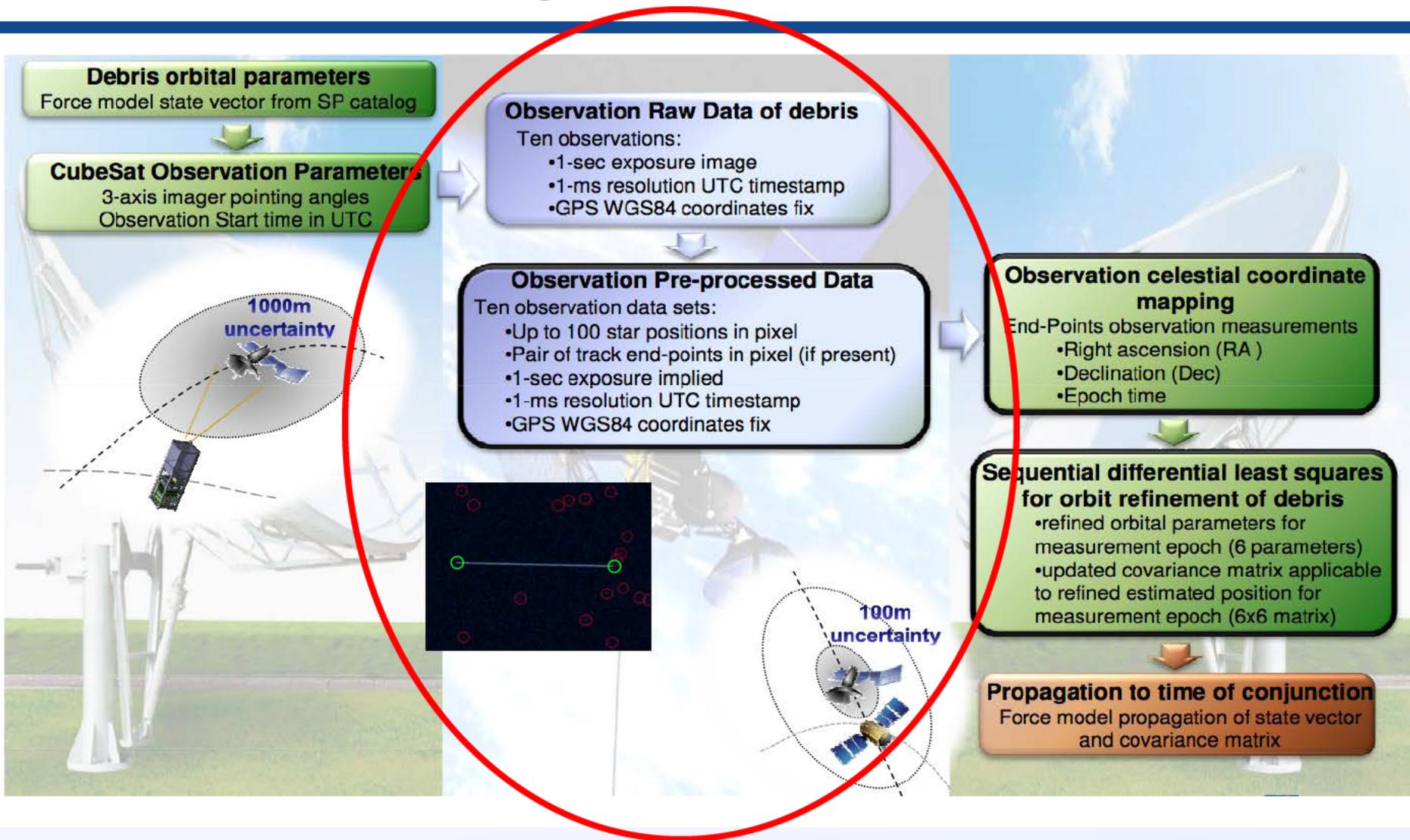
# Enter STARE

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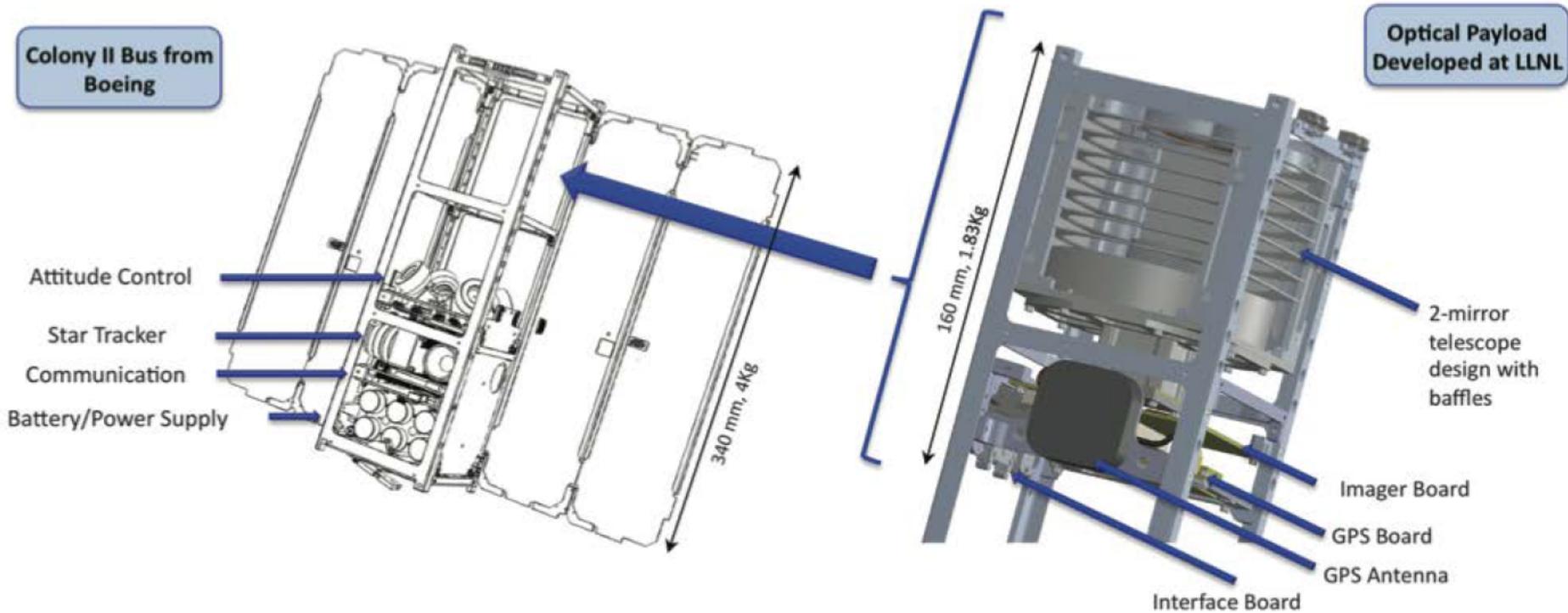
**S**pace-based  
**T**elescopes for  
**A**ctionable  
**R**efinement of  
**E**phemeris



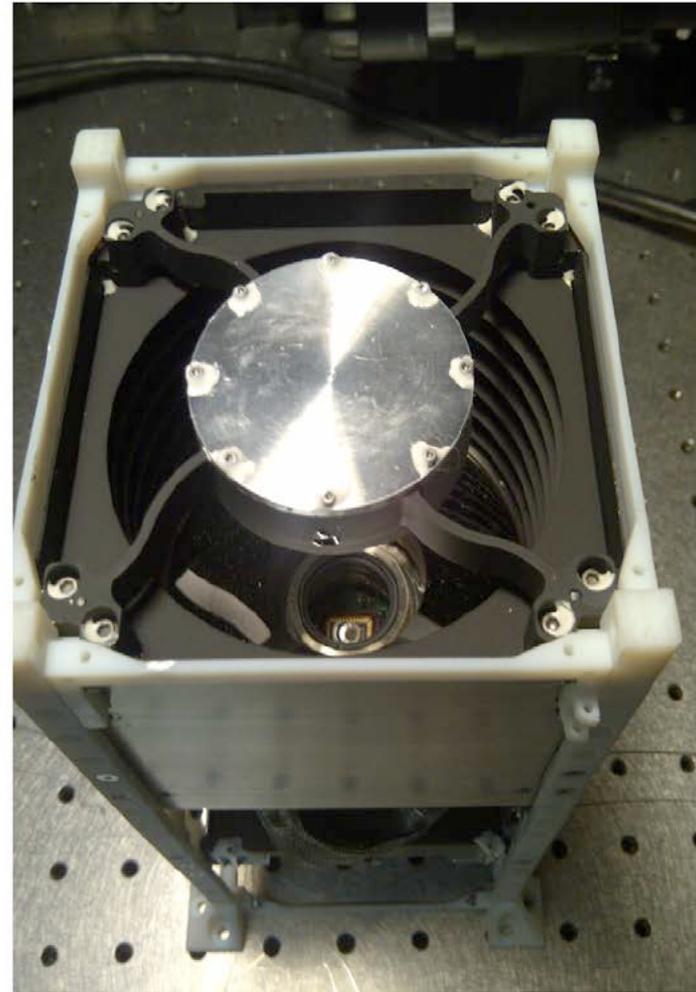
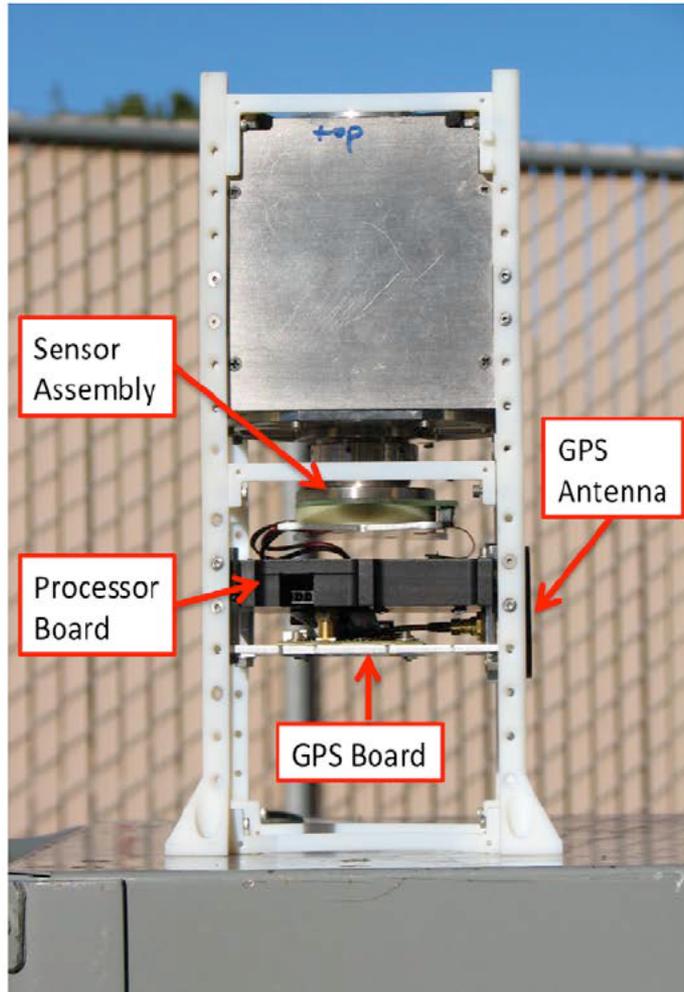
# STARE Processing and Data Flow



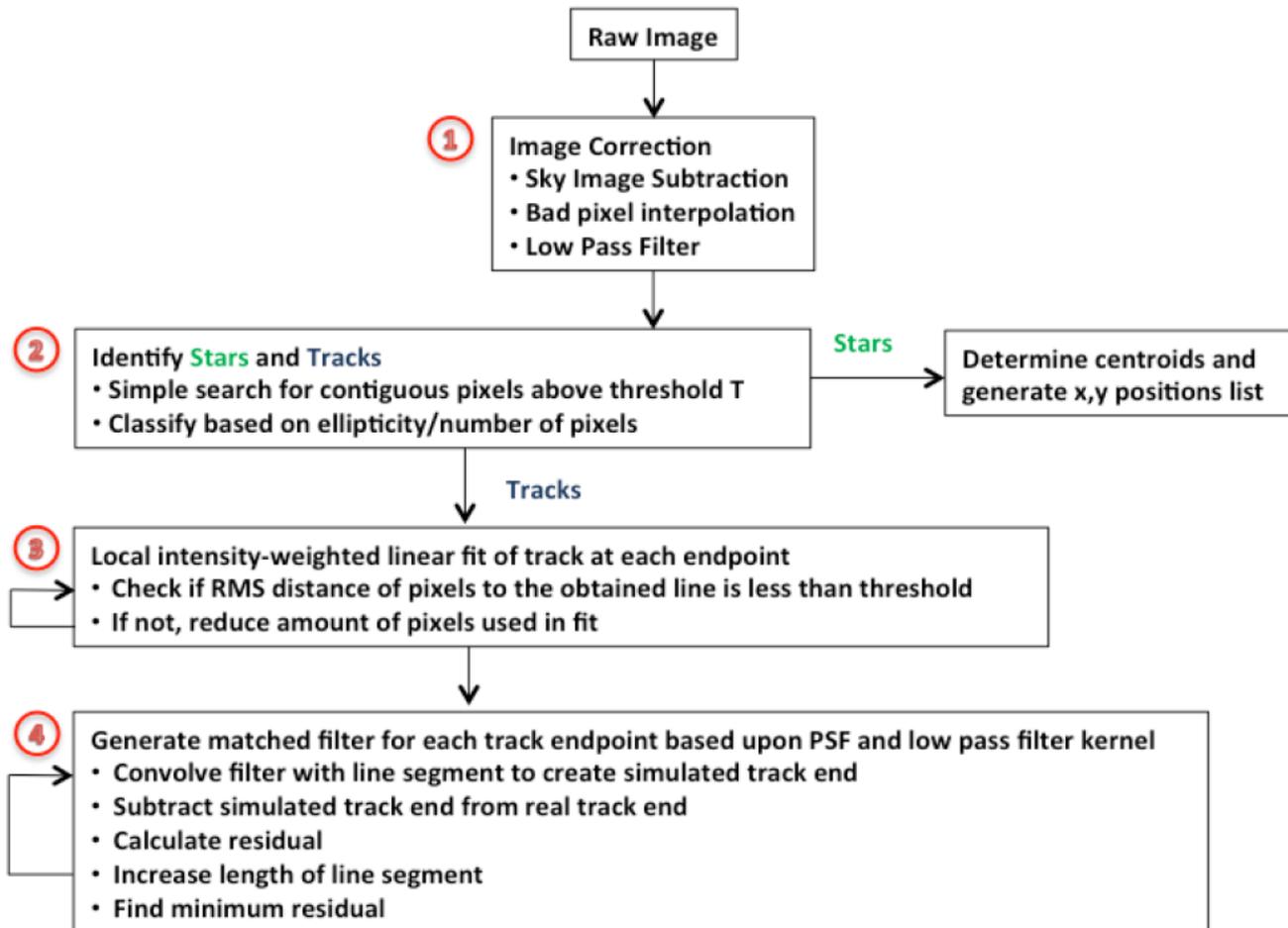
# STARE Satellite - Concept



# STARE Payload - Pictures

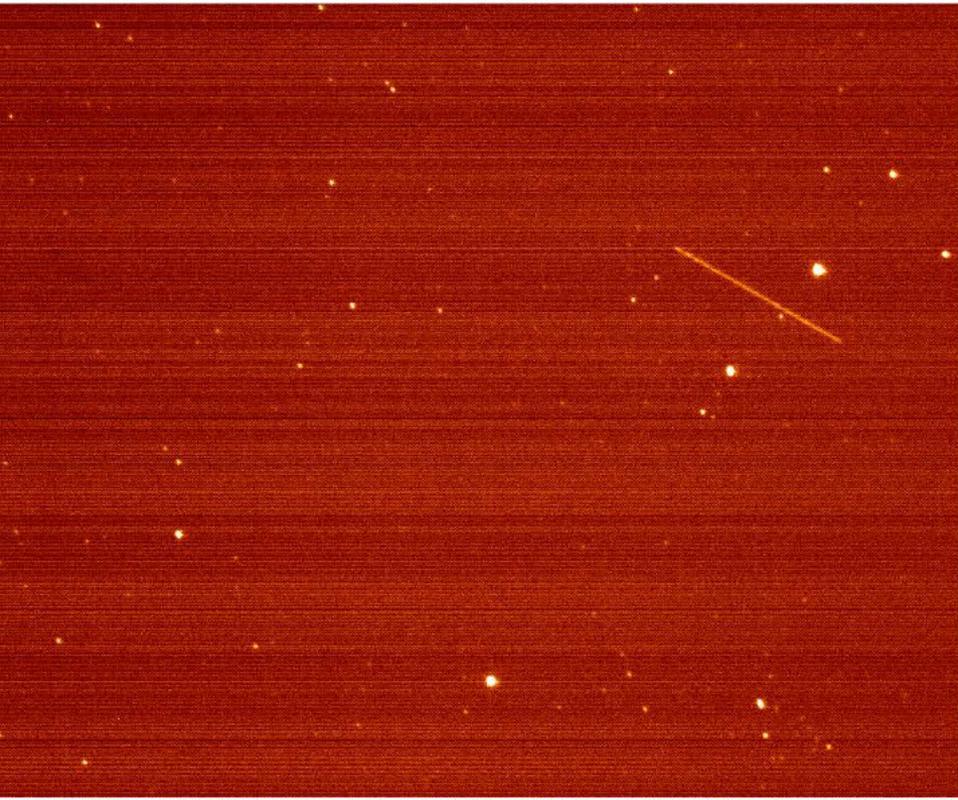


# Optical Payload: On-Board Image Processing



# ① Image Correction

**Before**



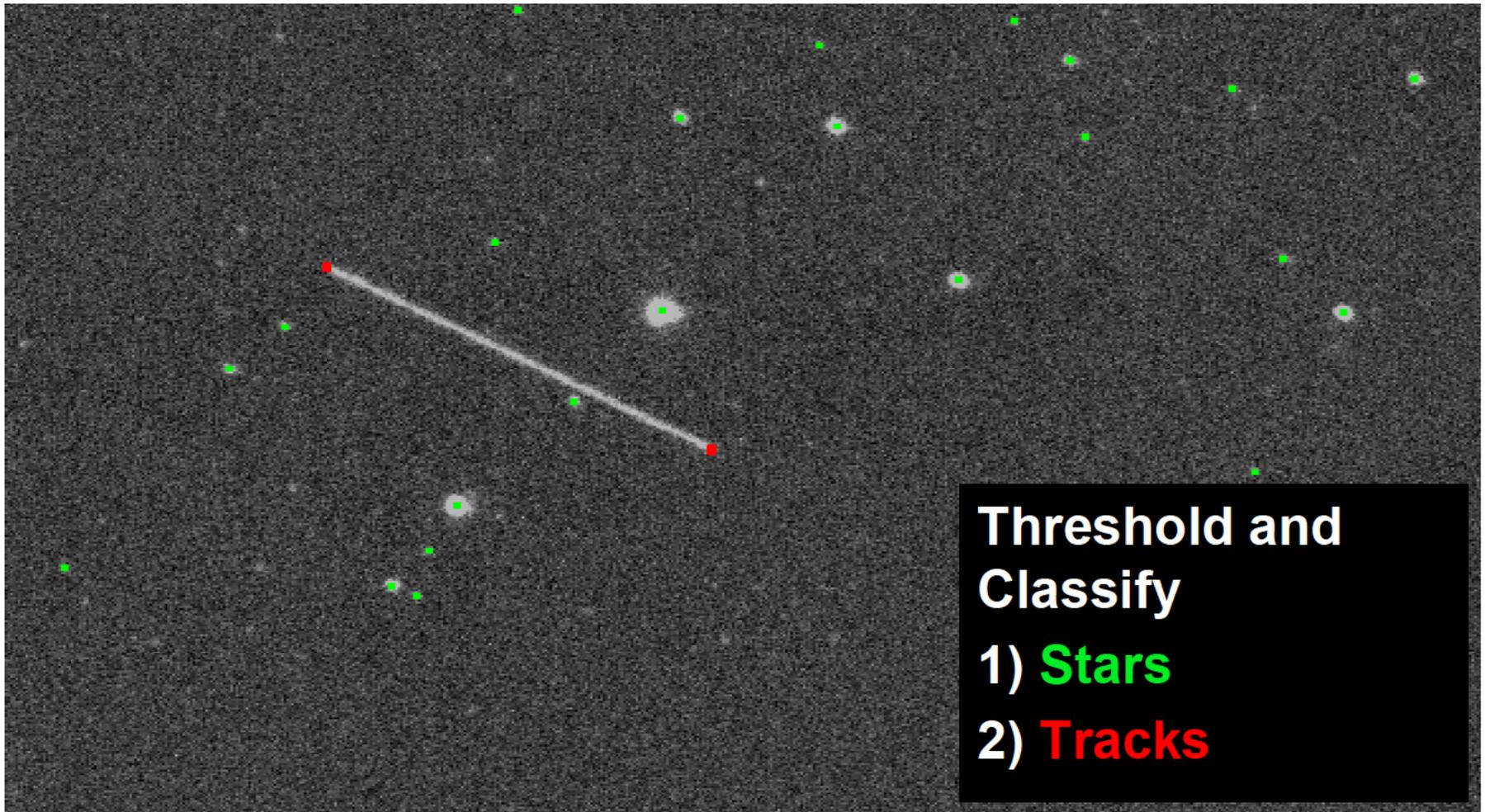
**After**



80 175 271 366 461 556 651 747 841

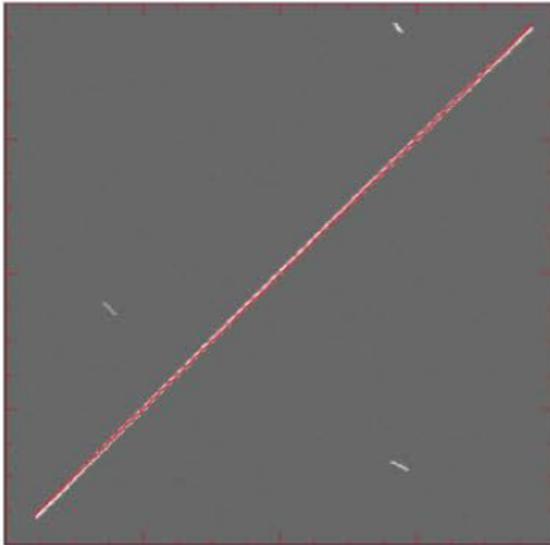


## ② Star and Track Detection

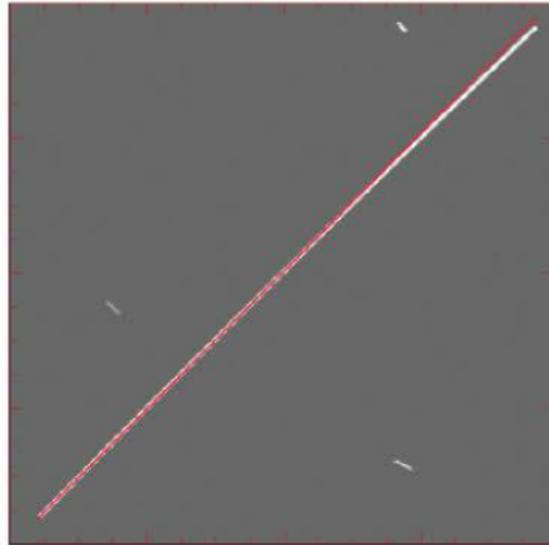


# ③ Track Fitting

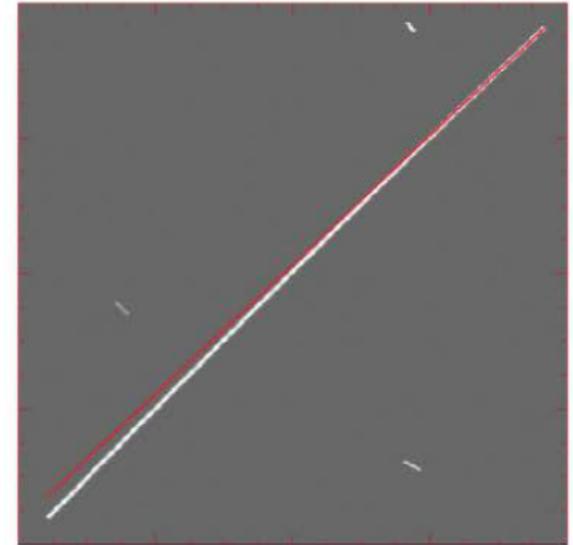
**Local Iterative Fitting at each end allows for curvature in track...**



Global Fit

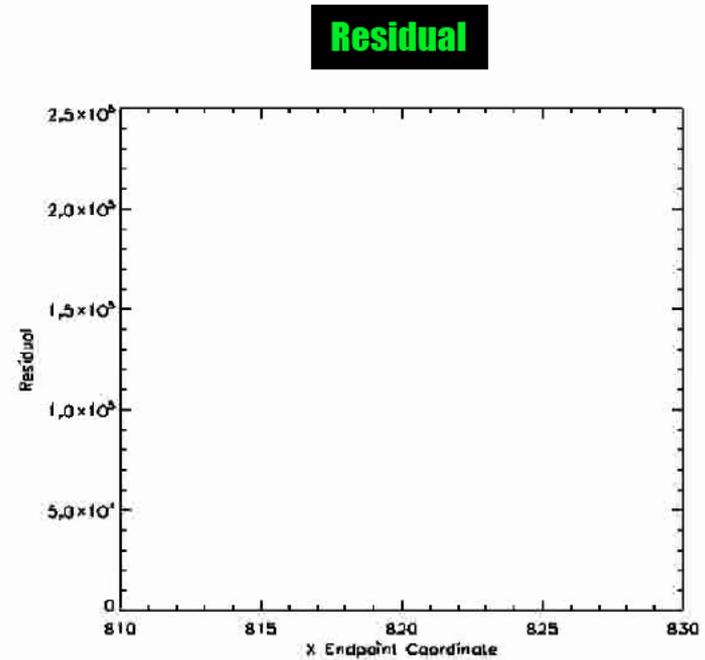
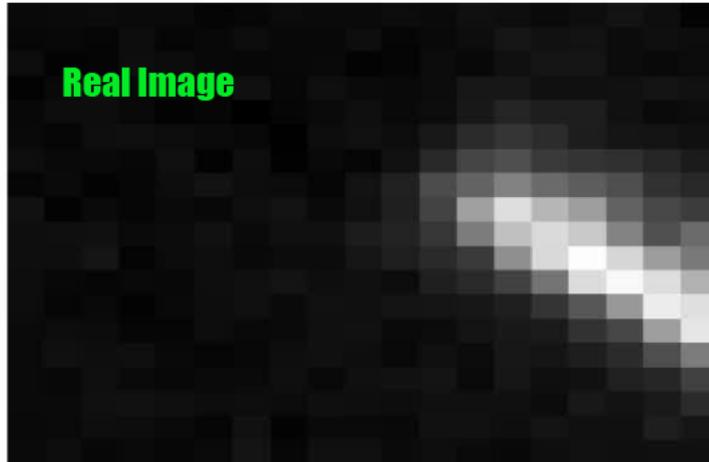


Left Endpoint Fit



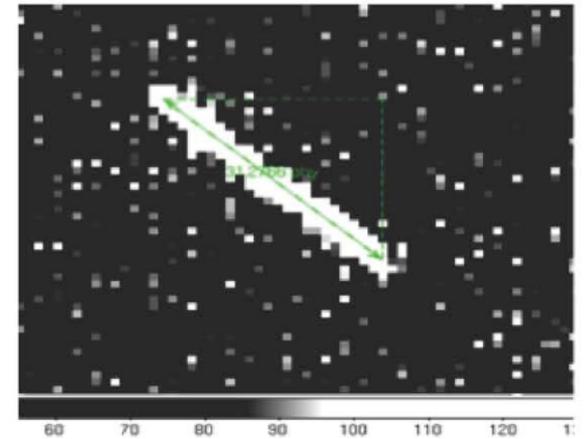
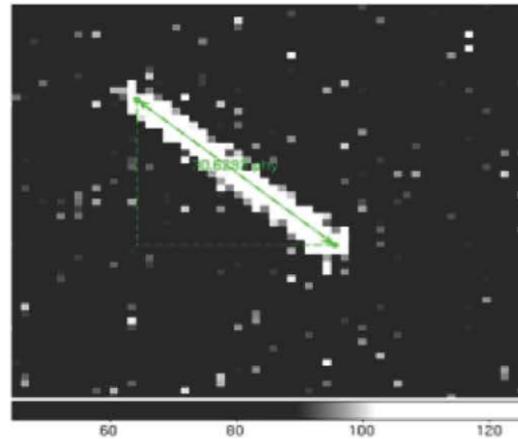
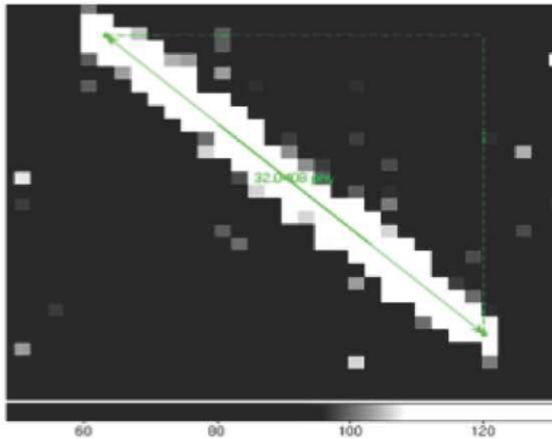
Right Endpoint Fit

# 4 Endpoint Determination



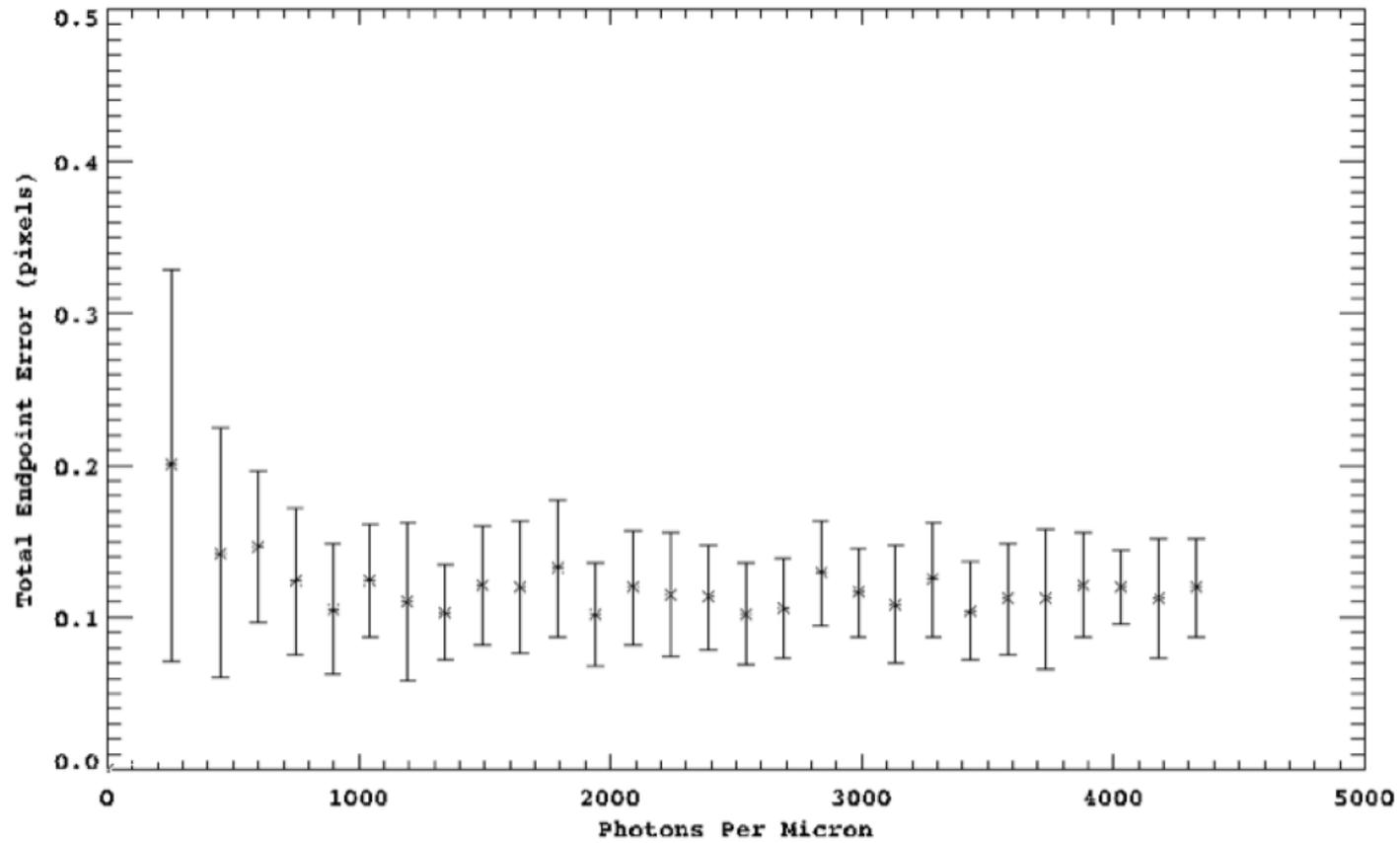
# Algorithm Test Results

**Test Results on real images show very good performance**



# Algorithm Test Results

## 400 simulated images



# Conclusions

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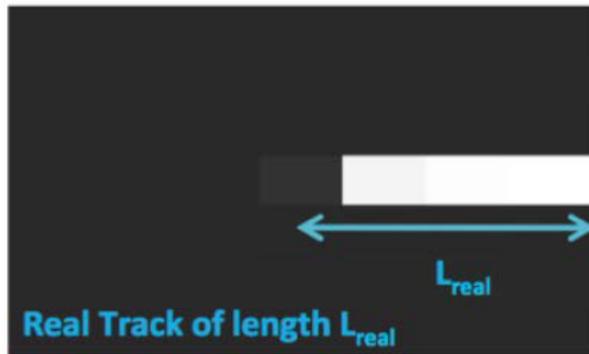
- STARE mission will refine orbits of space debris and satellites down to 100 meter accuracy
  - About 0.8-1.0 pixel accuracy needed
- Endpoint detection algorithm allows for 0.1 pixel accuracy



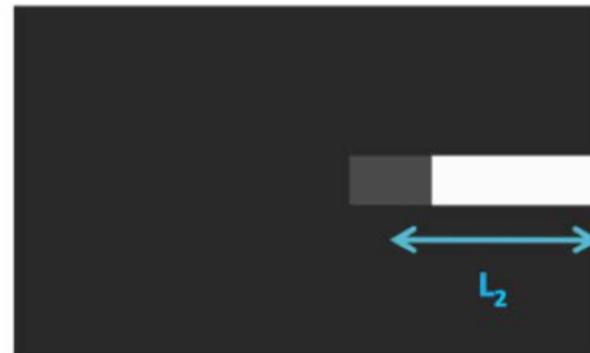
# Image Processing: Endpoint Determination

## Fit endpoints with track segment convolved with PSF

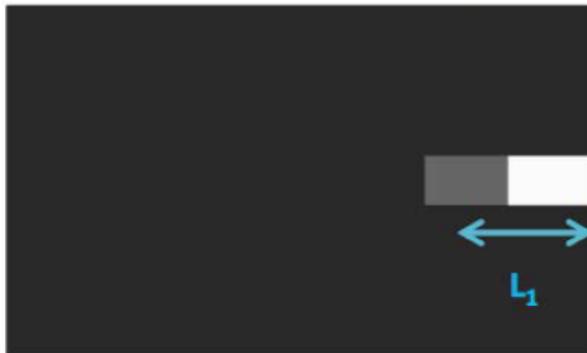
1) Start with real track



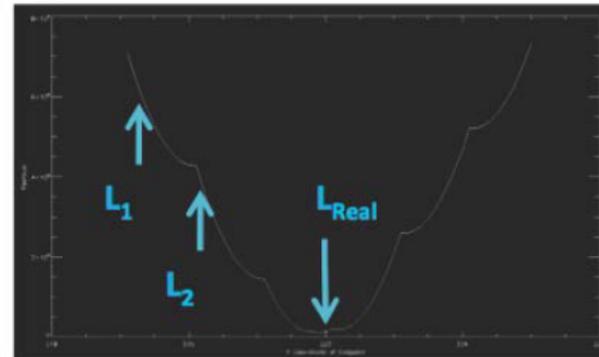
3) Increase length to  $L_2$



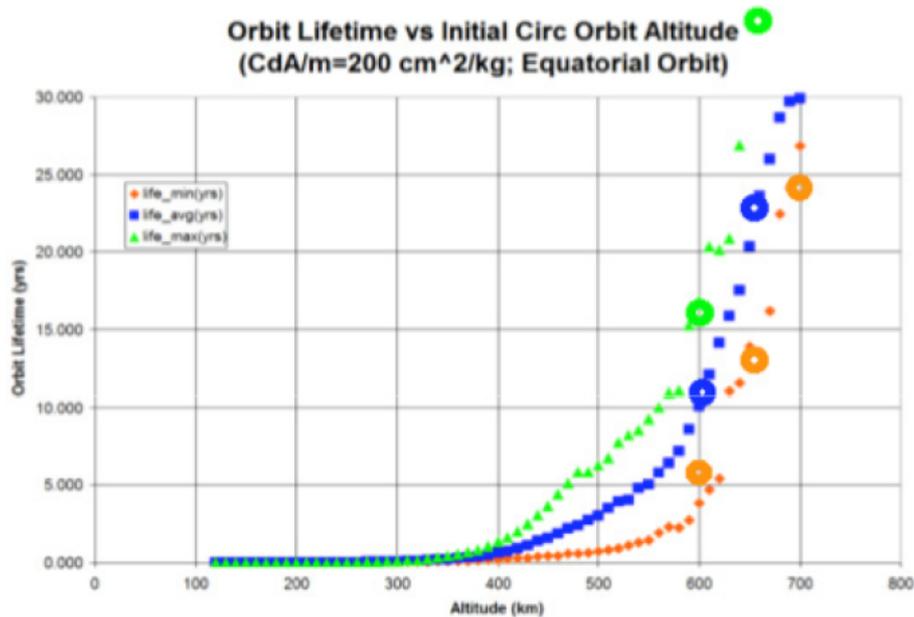
2) Generate track of length  $L_1$



4) Find minimum in residual



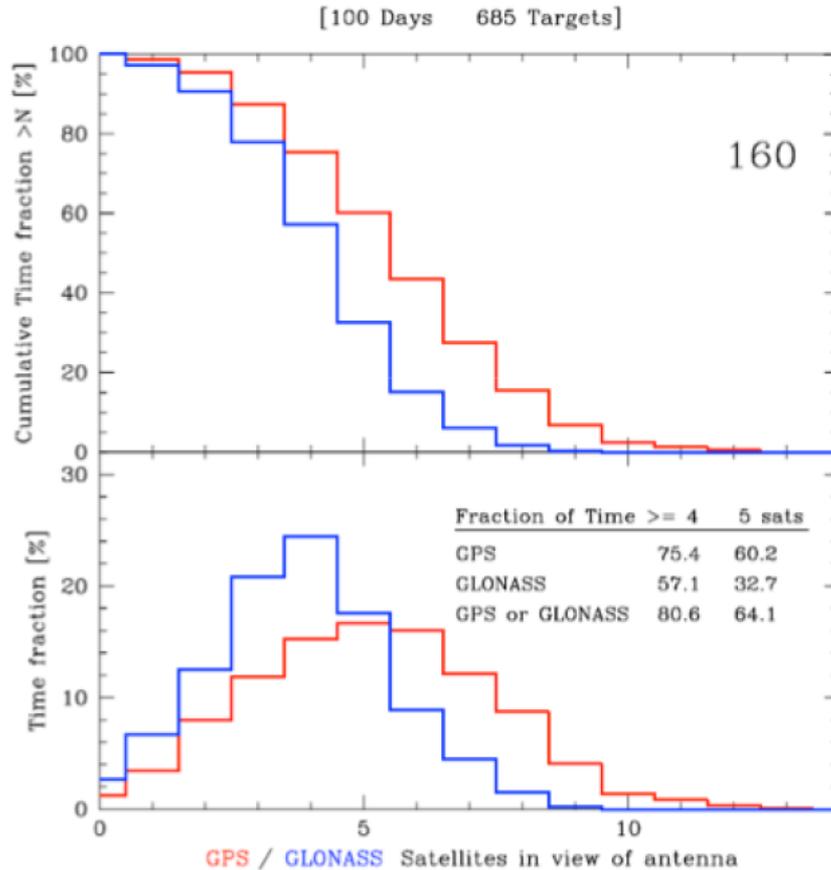
# Additional Slides



*Taken from "Space Systems – determining orbit lifetime", 2007, ISO International Standard working document, ref ISO/WD/27852, and LLNL computation (Wim D.)*

Surface Area [m <sup>2</sup> ]	Average [years]	Minimum [years]	Maximum [years]
0.03 (3U only)	57.0	31.1	>100
0.05	38.8	19.7	55.8
0.10	20.0	10.4	32.2
0.14 (Baseline eff)	14.6	7.5	23.3
0.15	13.6	7.0	22.0
0.21 (Baseline max)	9.9	5.0	16.0

# Additional Slides



- 700km polar orbit
- Representative observation schedule for 100 days
- Side antenna with expected effective angle in space of < 172degrees