Large-Scale Parallel Simulations of Distributed Detection Algorithms for Collaborative Autonomous Sensor Networks

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Why Distributed Detection?

- Cost lots of cheap sensors rather than one big one
- Reliability wider coverage area, can suffer attrition
- Performance approaches that of centralized with proper choice of a test statistic

Take Measurements at Each Sensor





Form Local Test Statistics





Fuse Neighbor State Information





Propagate Information Across the Network







Trade Latency for Communications Overhead



Convergence is reached when $x_1^K = x_2^K = ... = x_N^K$





Data Falsification by Compromised Nodes







Why ns-3?

- Discrete-event network simulator intended for research use
- Free software licensed under GNU GPLv2
- Used in over 1000 peer-reviewed publications
- Publicly available models to extend functionality
- Compares favorably to other simulation tools
- Has been shown to scale with parallelization



Computing Hardware

- My Computer
 - MacBook Air, Early 2015
 - 2 cores



- My Other Computer
 - CTS-1 Commodity Cluster
 - 96768 cores



More info: https://computation.llnl.gov/computers/commodity-clusters



Notional Scenario

- 1000 observer nodes
- 1 source node
- 10 km x 10 km x 3 km region of interest
- Observers set at elevations from 10 m to 3 km
- Source set on the ground





Centralized vs. Decentralized Performance



Convergence achieved within about 20-40 rounds



When You Add a Byzantine...



Only 1 Byzantine degrades a network of 1000 nodes



Robust ADMM Helps Mitigates the Attack



Greater impact on smaller networks



Small Performance Hit Without Byzantines



Better than dealing with a Byzantine, though!





- In a no-cyber world, decentralized performance is great
- Byzantine attacks can severely degrade performance
- Robust ADMM approach can help mitigate loss
- Small losses without Byzantines present
- Which would you rather deal with?

More questions? Email: yen6@llnl.gov



