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FUSION OF X-RAY AND ULTRASOUND IMAGES FOR AS-BUILT MODELING

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Agenda

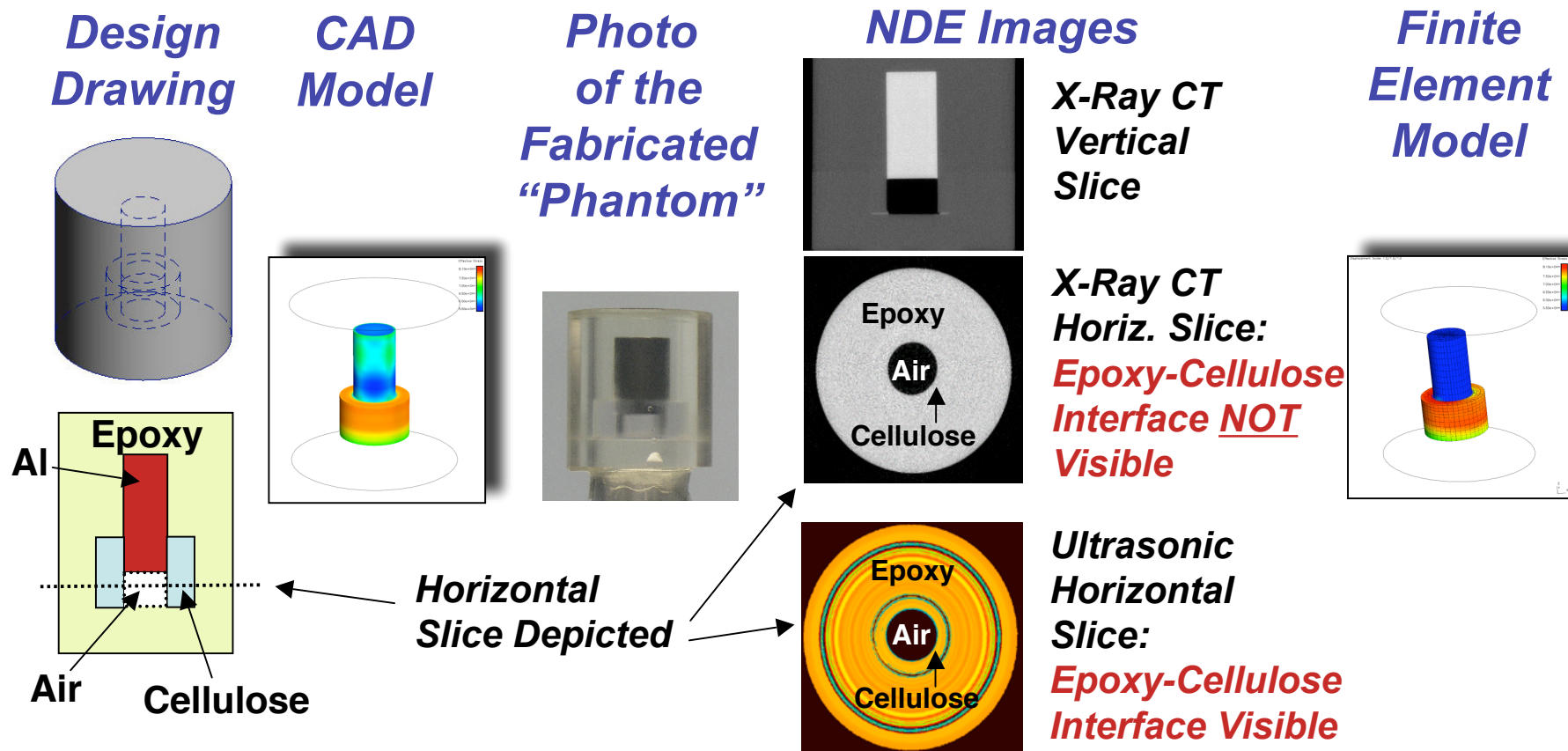


- **Problem Definition**
- **Controlled Experiments with a “Phantom” Part**
- **Registration and Fusion Algorithms**
- **Experimental Results**
- **Conclusions**

ME Techbase, "Process Development and Implementation of NDE-FEA Coupling for Numerical Analysis"



- Created a RD&T Roadmap for Engineering Centers (CNDC and CCE)
- Multi-modal Sensor Fusion and Flaw Recognition for **"As-Built Modeling"**
- Processed X-Ray CT and Ultrasonic images from a known "phantom"



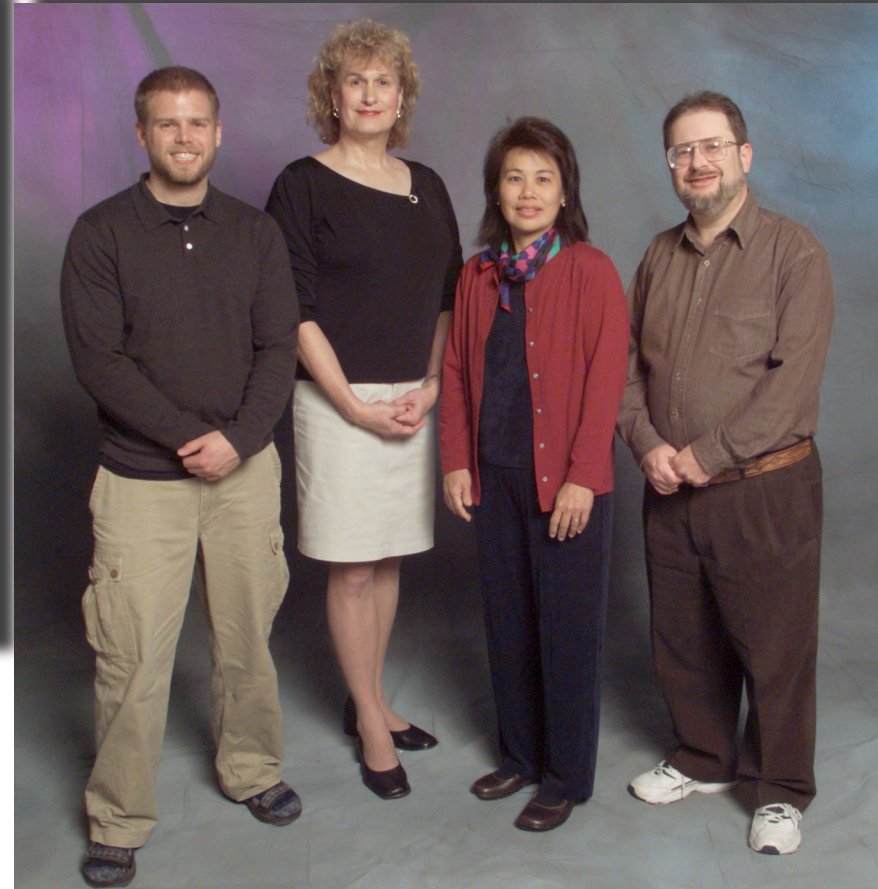
As-Built Modeling: Fabrication Errors Can Sometimes Be Significant



As-Designed



As-Built



ENGINEERING CCE AND CNDC TECHBASE '04 PROJECT, "PROCESS DEVELOPMENT AND IMPLEMENTATION OF NDE-FEA COUPLING FOR NUMERICAL ANALYSIS," ED KOKKO, GRACE CLARK, DIANE CHINN, DAVE CHAMBERS

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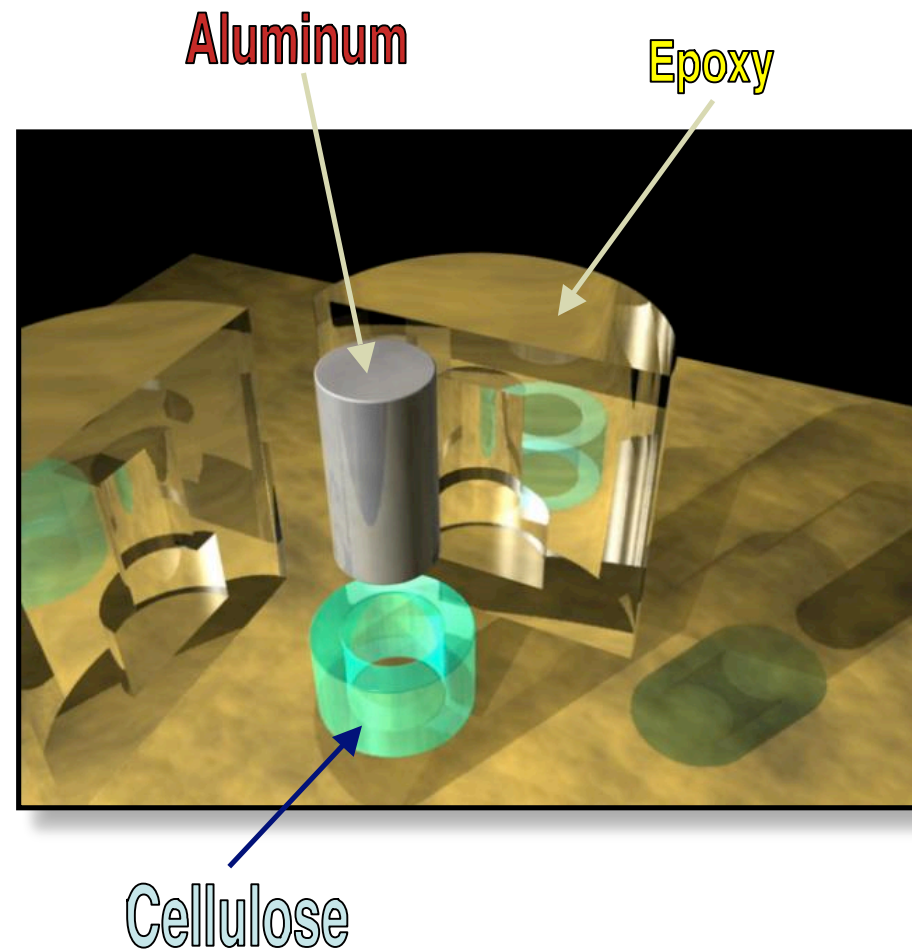
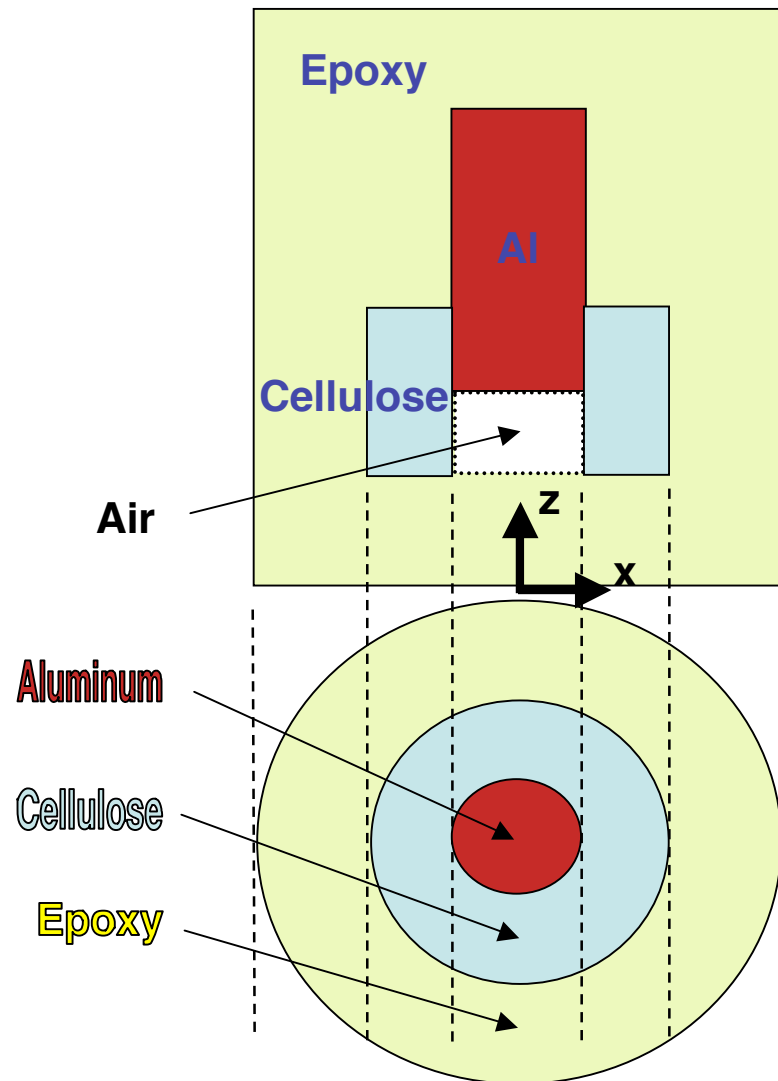


The Literature Contains No Fusion of X-Ray and Ultrasound NDE Imagery



- The medical literature contains some fusion results, but they are not generally useful for NDE:
 - Allowable power levels are much lower for medicine
 - Attenuation effects are much different in medicine
 - Qualitative results (visual inspection) are usually sufficient
 - Fiducial marking is routine in medicine, but often not possible in NDE at LLNL
- Image registration is the “long pole in the tent” for fusing X-ray and Ultrasound NDE Images - Attempts have been unsuccessful
 - There are separate scanning systems for X-ray and Ultrasound, so mechanical registration is impossible
 - Image reconstruction and registration are coupled
 - Scaling the UT image requires ray tracing, event picking, and velocity estimation (as in seismic processing)
 - Difficult to automate

Our Test Part Consists of 3 Concentric Cylinders Made of **Aluminum**, **Cellulose** and **Epoxy**



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Slide: Grace Clark and Mike Loomis

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CT and UT Measure Different Material Properties. Each Modality Has **Strengths** and **Weaknesses**.

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CT (X-Rays)

Measures X-Ray Attenuation

$$A = f[E_A, \rho, Z]$$

where :

E_A = Energy Applied

ρ = Density

Z = Atomic Number (# protons)

Strengths:

- A strong function of Z ($\sim Z^r$)
- High spatial resolution (good for observing part geometry)
- Spatial scaling is automatic

Weaknesses:

- *Not very sensitive to changes in density - Not good for detecting closed cracks*

UT (Ultrasonics)

Measures reflected acoustic energy

$$R = g[\rho, E]$$

where :

ρ = Density

E = Modulus of Elasticity

= Young's Modulus

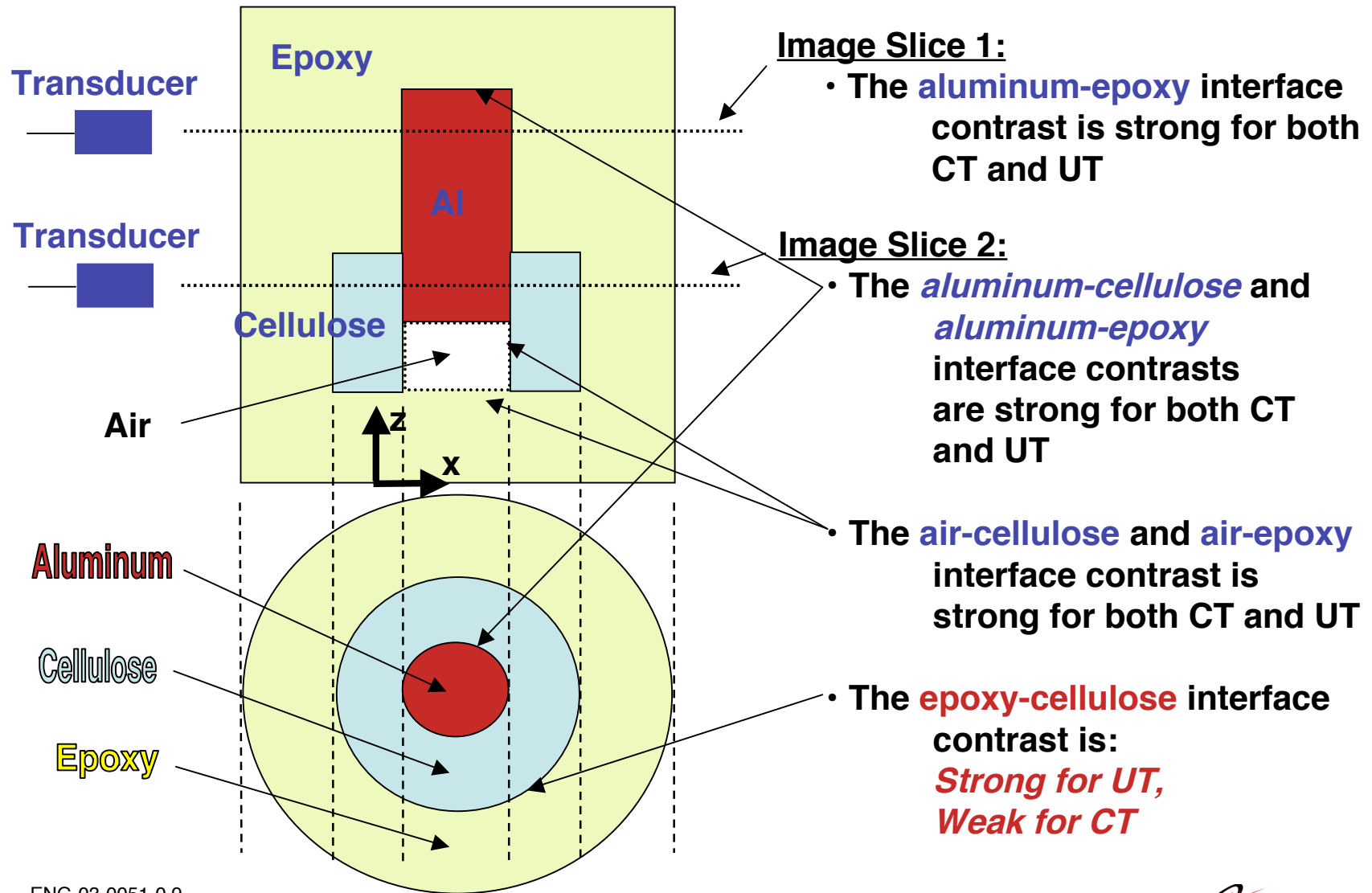
Strengths:

- *Good for detecting small changes in density and modulus*
- *Good for detecting closed cracks*

Weaknesses:

- *Low spatial resolution due to temporal “ringing” of band-limited ultrasonic transducers*
- *Spatial scaling is complex, difficult*

Two Image “Slices” Demonstrate the Strengths and Weaknesses of CT and UT



The Epoxy-Cellulose Interface Has **Low Contrast With CT**, but **Much Higher Contrast With UT**



The Epoxy - Cellulose Interface:

- Epoxy and Cellulose have approximately the same density and modulus:

Composition

► Density:

$$\rho_{Epoxy} \approx \rho_{Cellulose}$$

► Coefficient of Elasticity:
(Young's Modulus)

$$E_{Epoxy} \approx E_{Cellulose}$$

► Atomic Number:

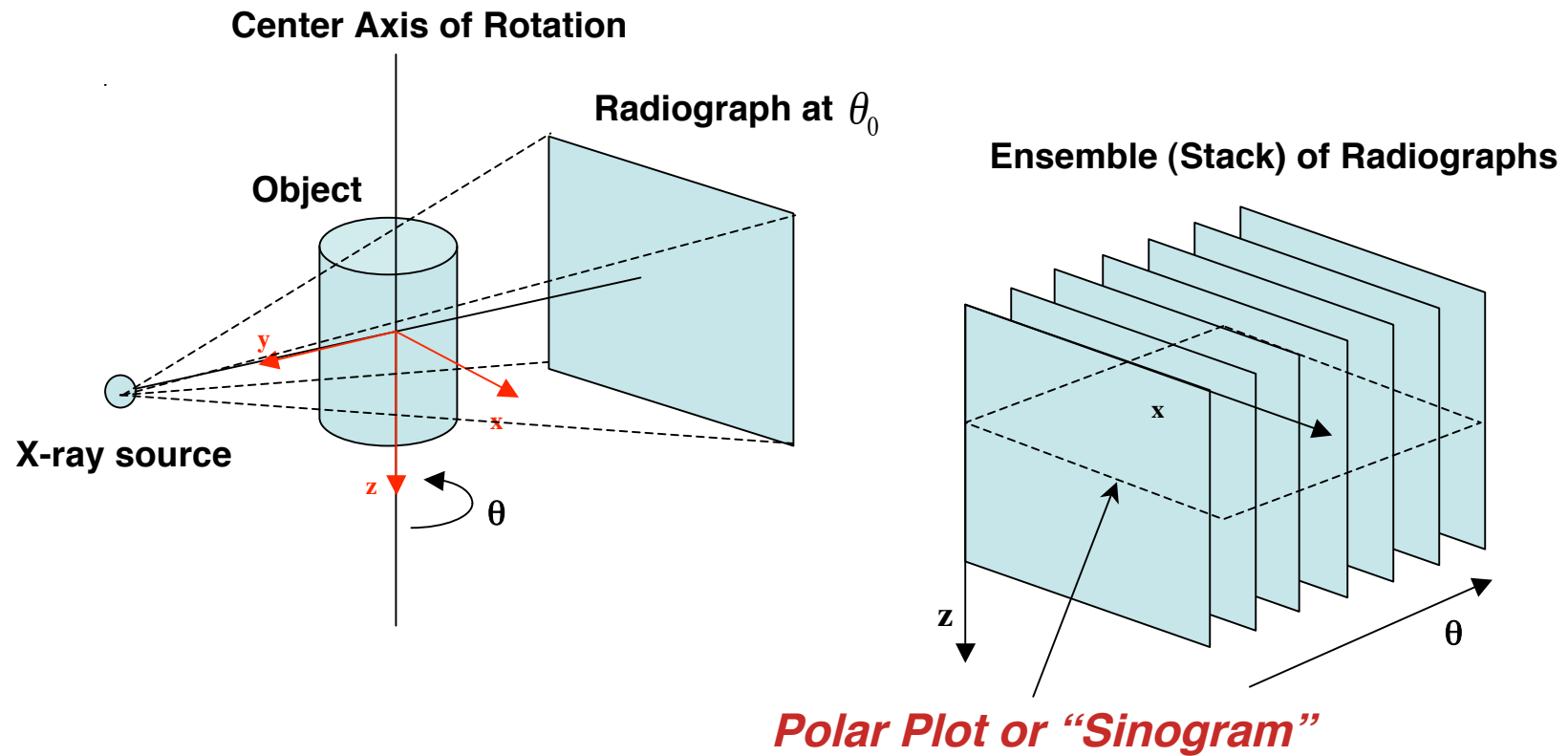
$$Z^{eff}_{Epoxy} \approx Z^{eff}_{Cellulose}$$



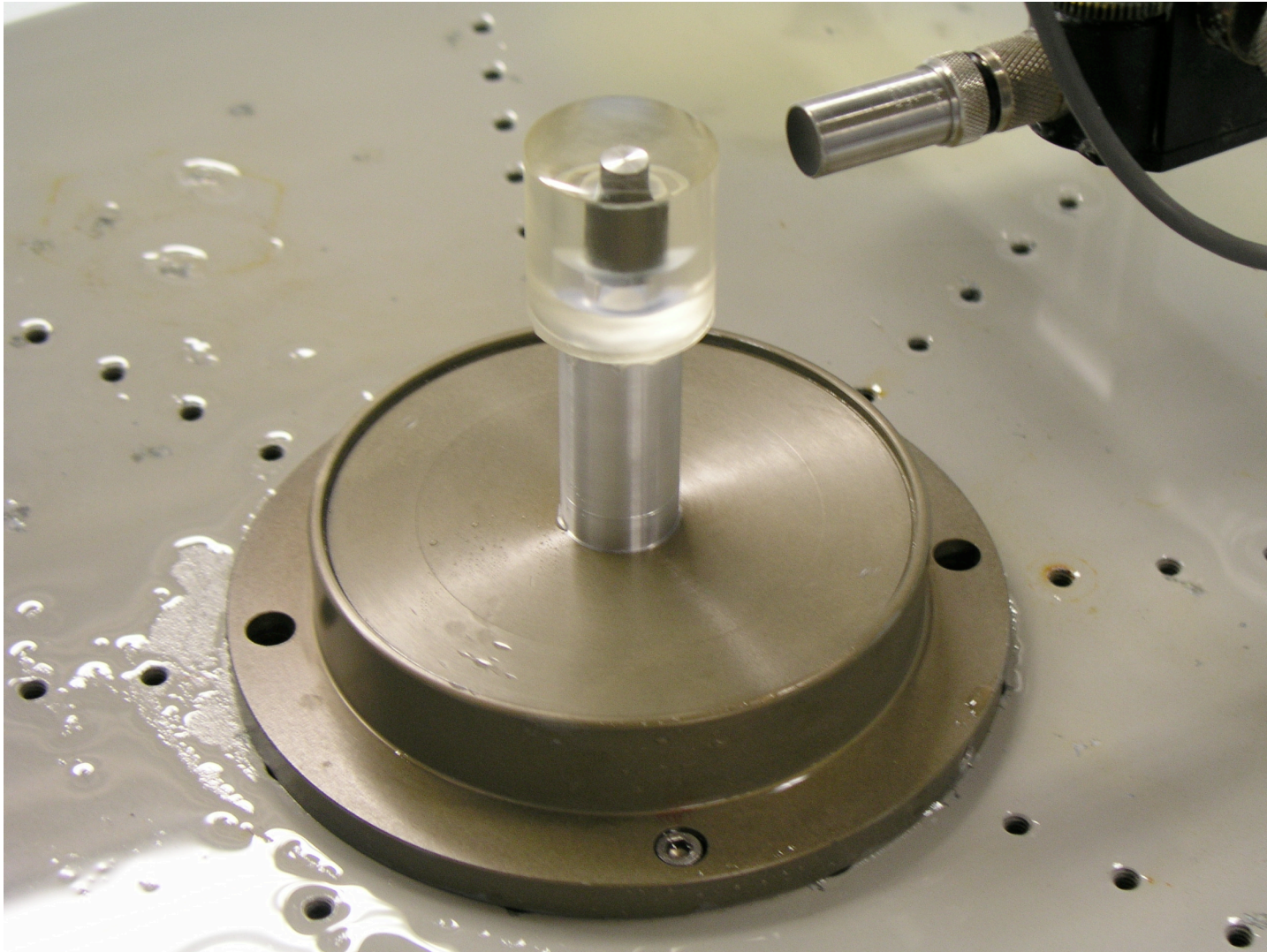
- UT can detect interfaces well
- CT is minimally effective for interface detection, good for geometry characterization

- The other interface contrasts are strong for both CT and UT

X-Ray Images (Radiographs) are Acquired by Fixing the X-Ray Source and Rotating the Object



Ultrasound Images are Acquired Using a Separate Scanning System: Source is Fixed, Object is Rotated

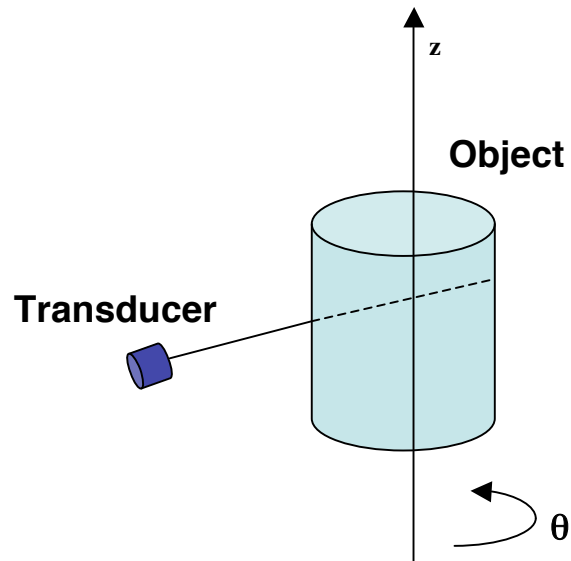


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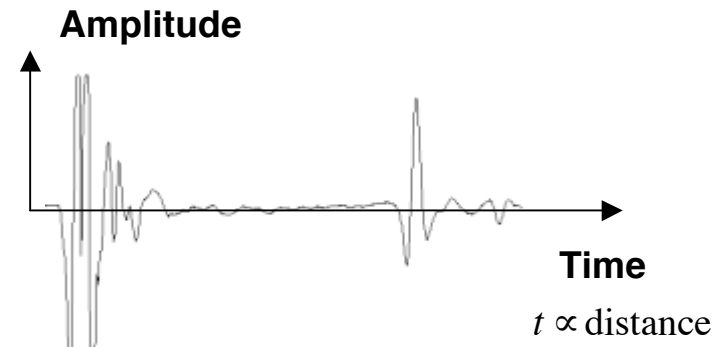
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***Ultrasound Images are Acquired in Pulse-Echo Mode,
Scanning the Transducer Vertically as the Part is Rotated***



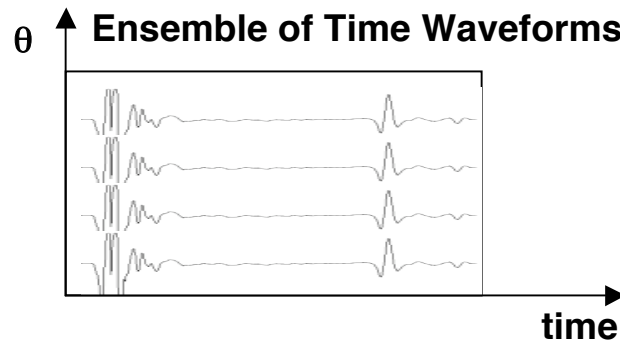
Raw A-scan (Time Waveform)



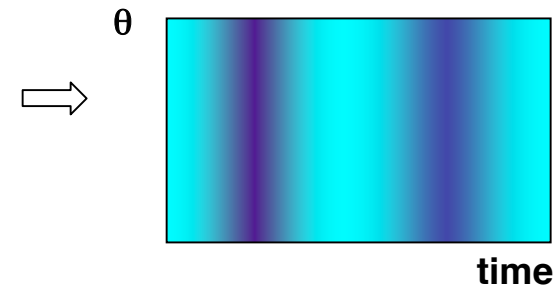
*An Ensemble of Ultrasonic A-Scans Forms a **B-Scan***



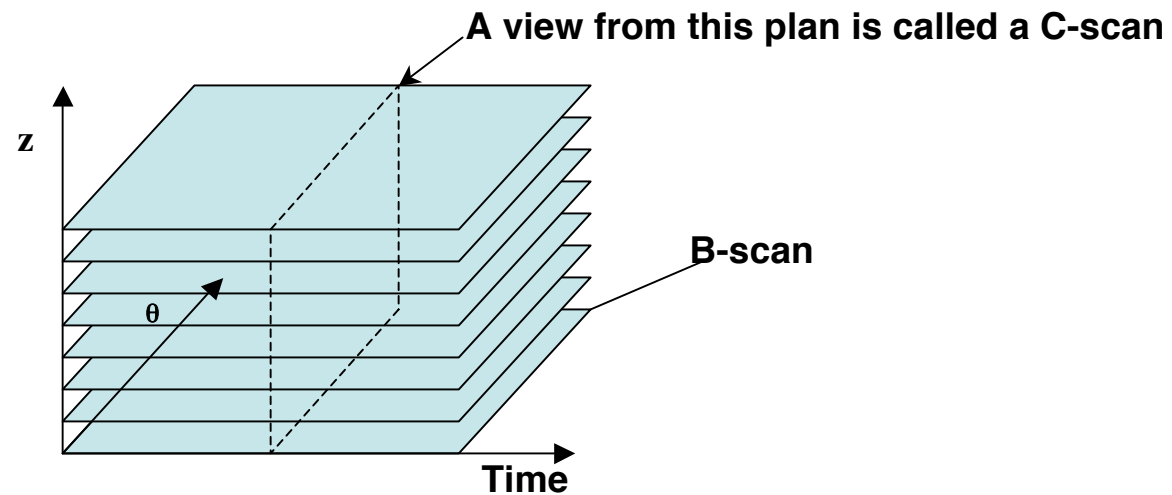
B-Scan Plotted as an Ensemble of Time Waveforms



B-Scan Plotted Using Pixel Intensity

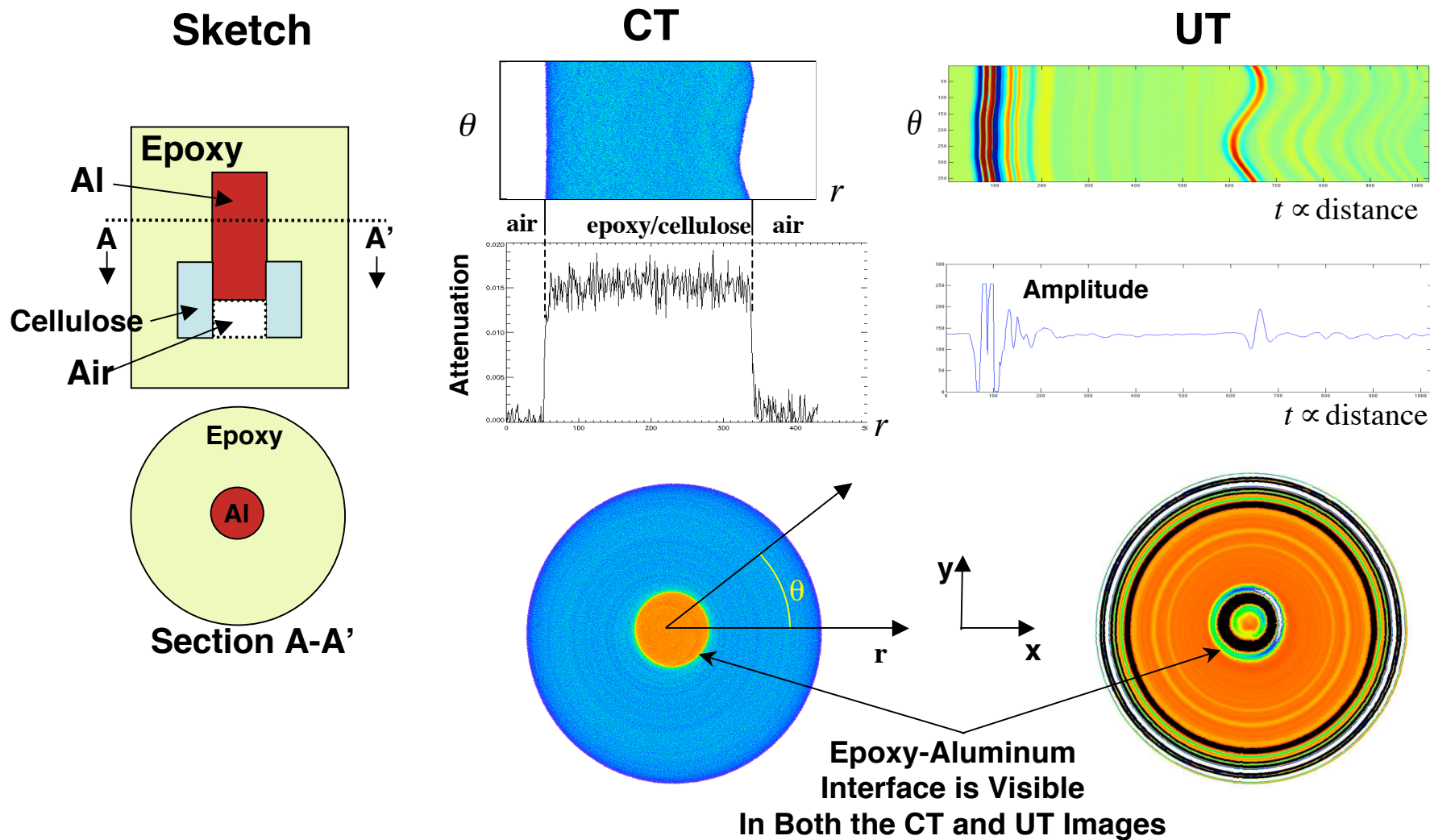


*An Ensemble of B-Scans forms a **3D Volume***



Summary of Horizontal Slice 40: Epoxy and Aluminum

Both CT and UT Show the Epoxy-Al Interface

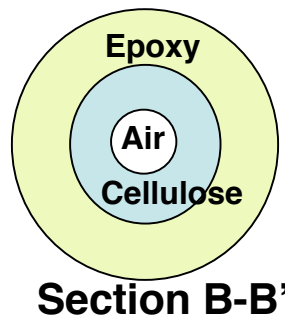
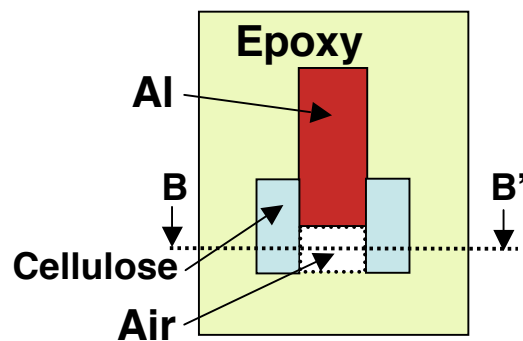


Summary of Horizontal Slice 20: Epoxy, Cellulose, Air

Cellulose-Epoxy Interface is Visible Only in the UT Image

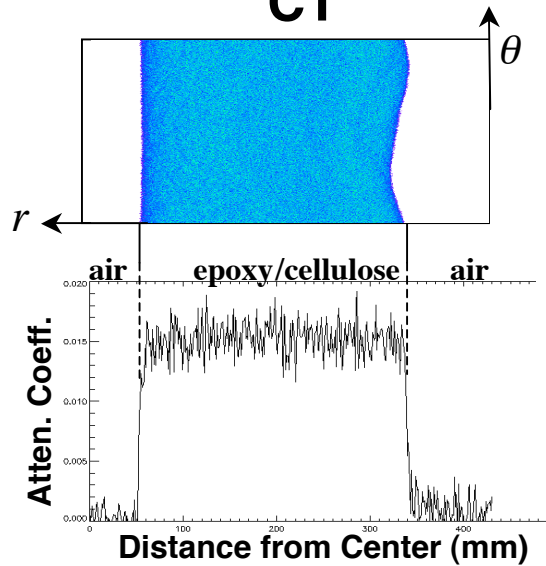


Sketch

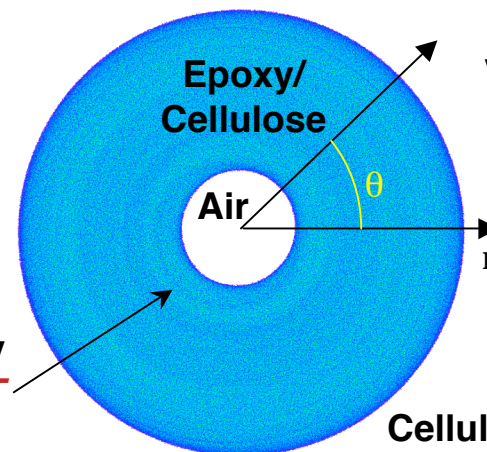
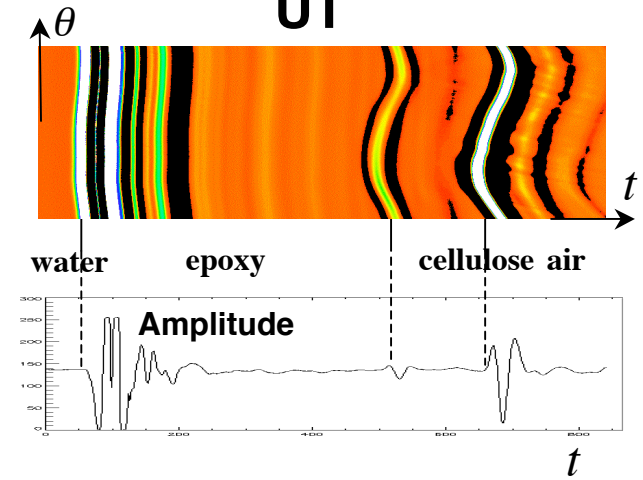


Cellulose-Epoxy Interface is **NOT** Delineated

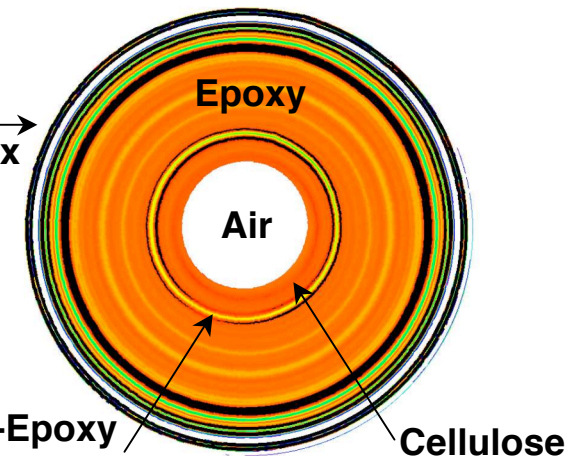
CT



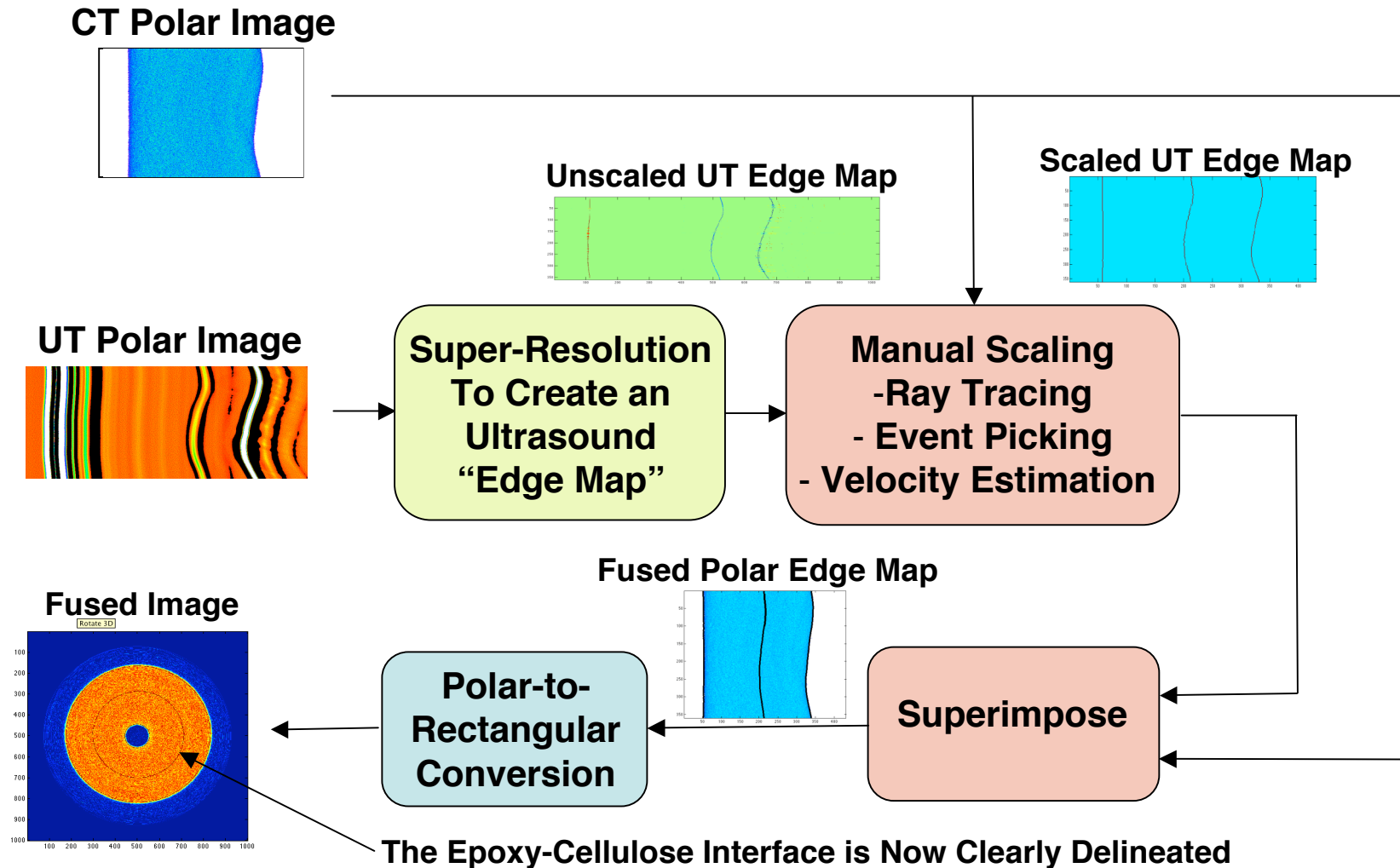
UT



Cellulose-Epoxy Interface is Clear



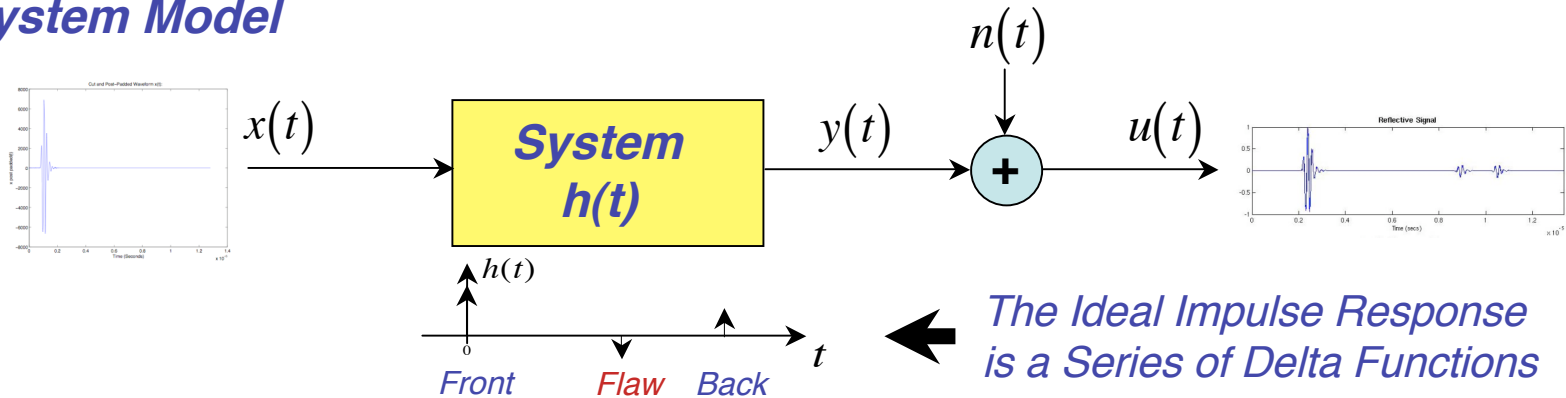
Suboptimal Semi-Manual Fusion: Build a “UT Edge Map” and Superimpose it on the CT Image



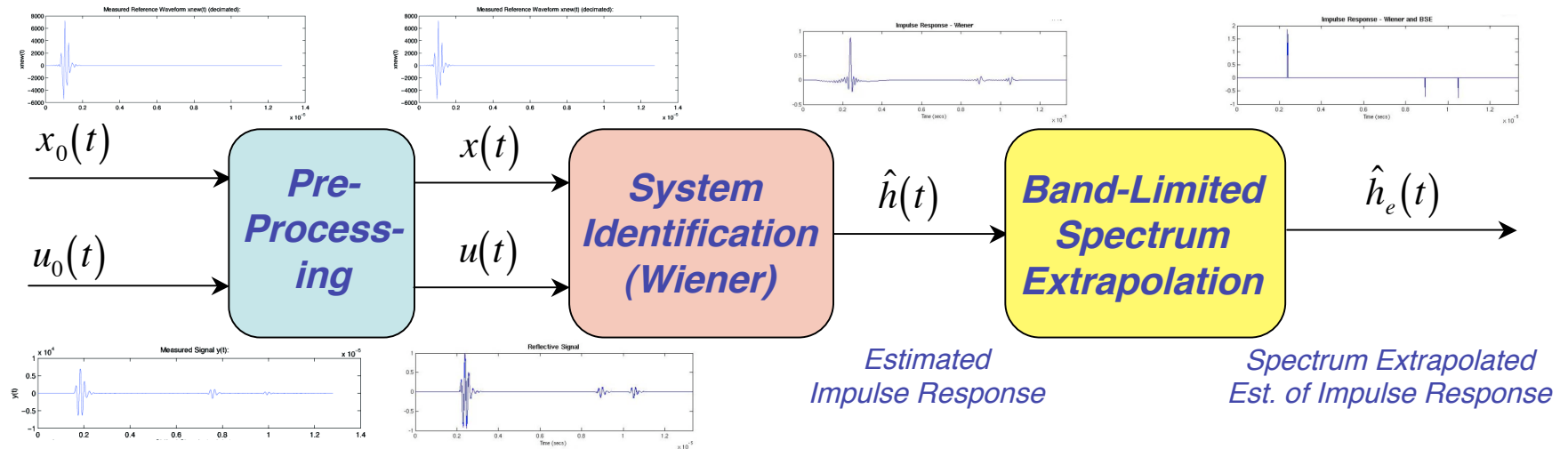
The *System Model* and *Super-Resolution Algorithms* Are Summarized in Block Diagrams



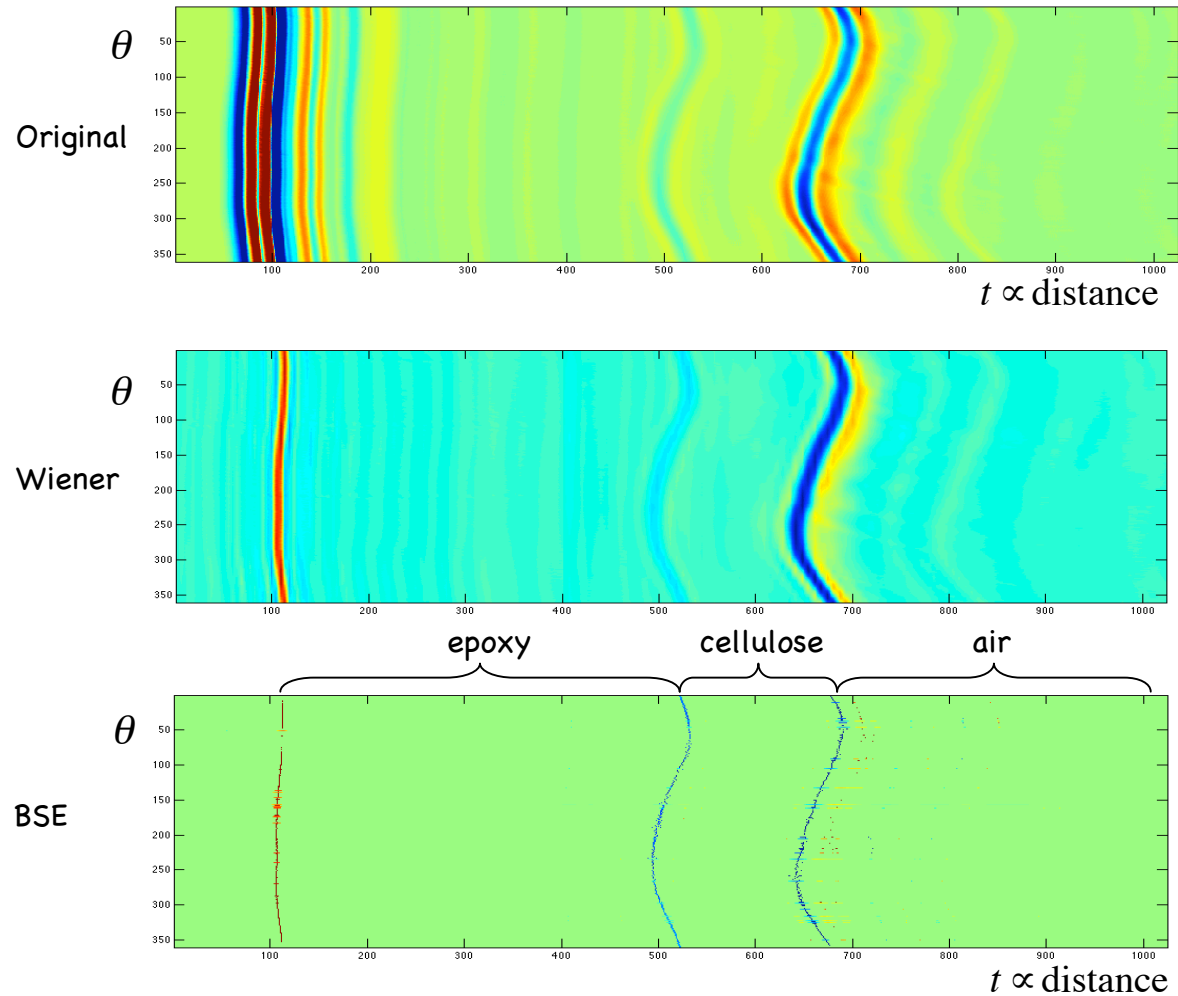
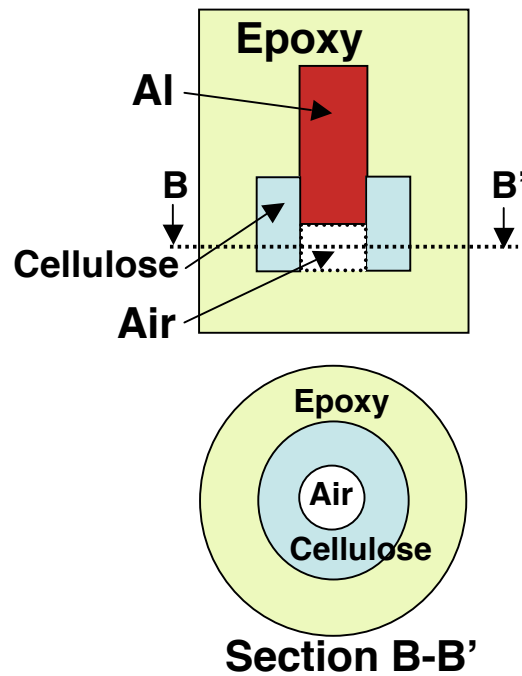
System Model



Super-Resolution Algorithms



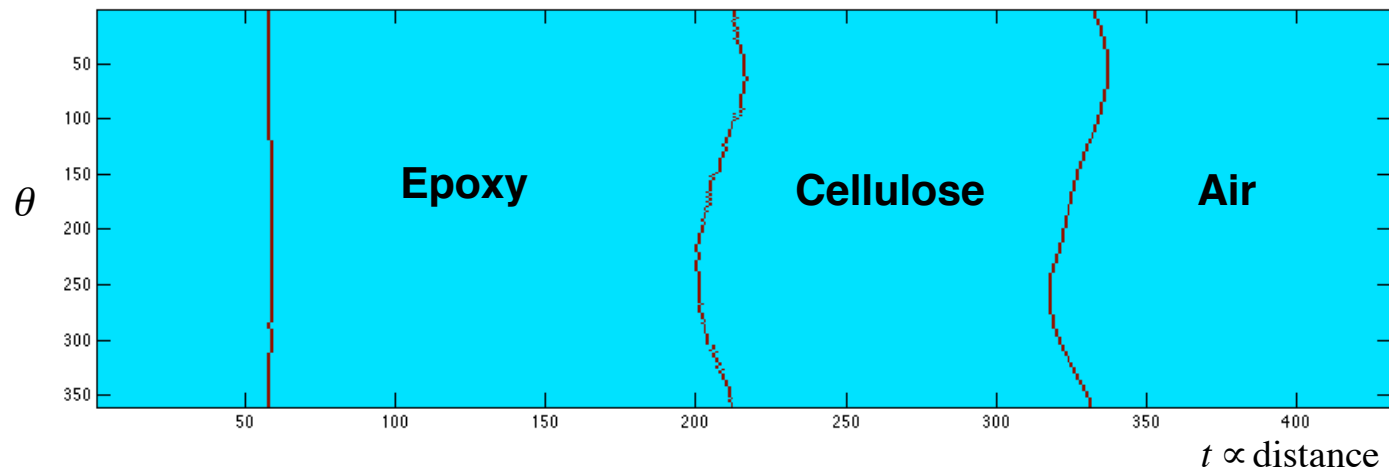
Super-Resolution Result: Resolution is Enhanced in the Ultrasound Polar Plots of *Slice 20*



An “*Ultrasound Edge Map*” Polar Plot is Created from *Slice 20* Using the Super-Resolution Results



By Manually Comparing the CT Image and the UT Edge Map,
A Spatially Scaled UT Edge Map can be Determined:
(*Ray Tracing, Event Picking and Velocity Estimation are Done Manually*)



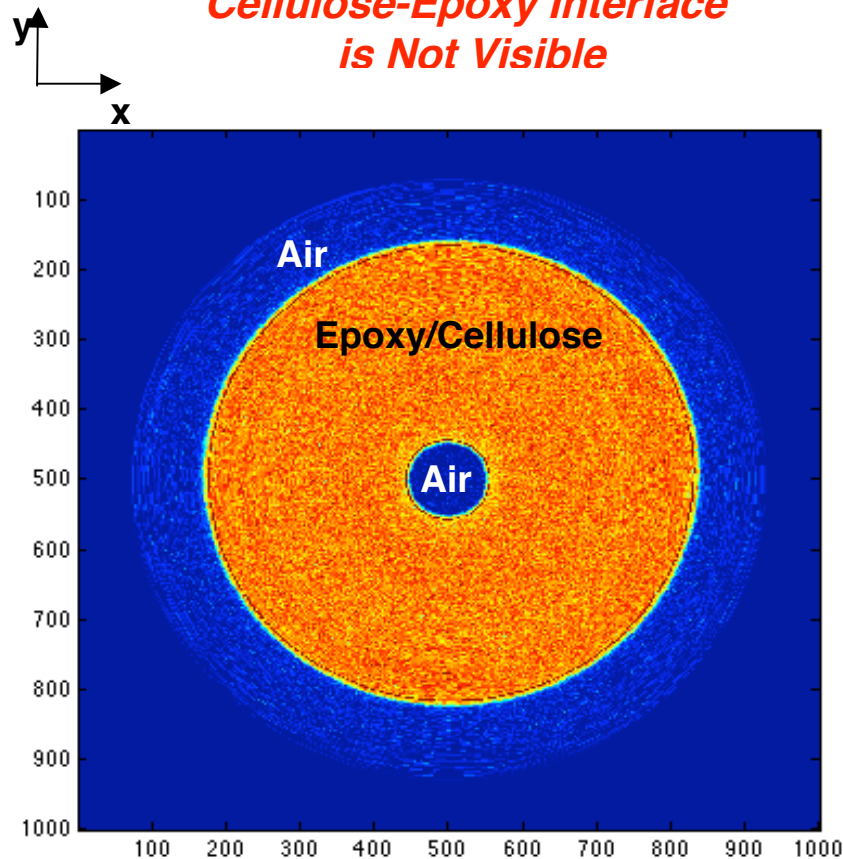
Fusion: The “*UT Edge Map*” is Superimposed on the CT Image of *Slice 20* to Show the Cellulose-Epoxy Interface



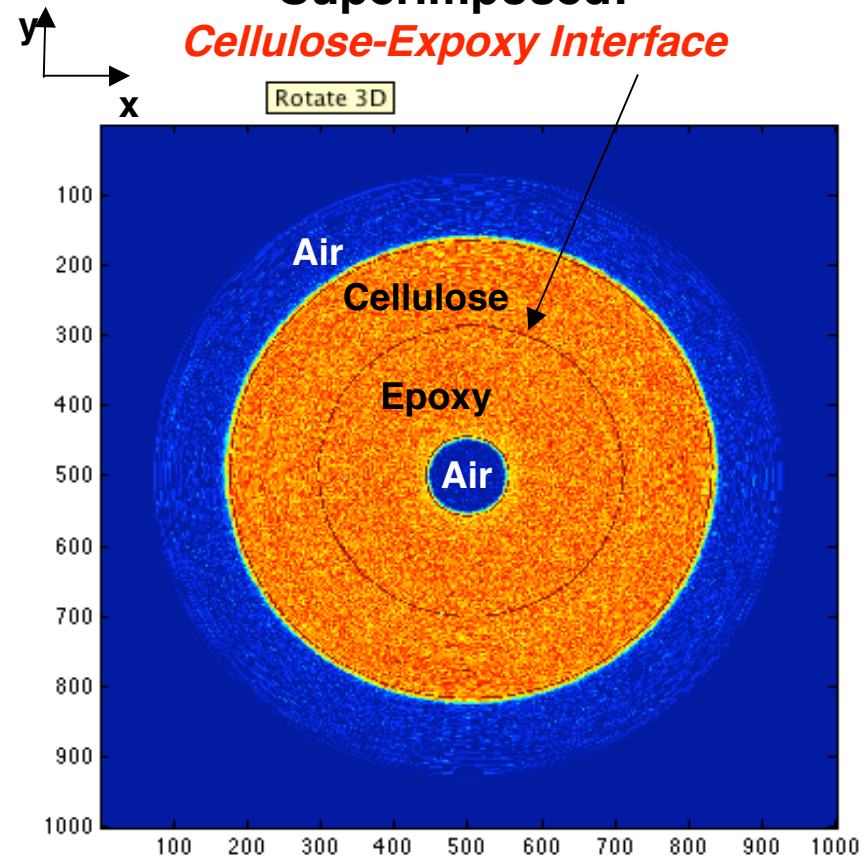
Slice 20

X-Ray CT Image:

*Cellulose-Epoxy Interface
is Not Visible*



X-Ray CT Image
with the “*UT Edge Map*”
Superimposed:
Cellulose-Epoxy Interface



Conclusions



- **We demonstrated a semi-manual method for fusing X-ray and Ultrasound images**
 - **Using super-resolution algorithms to build an “edge map”**
 - **Manually performing ray tracing, even picking, and velocity estimation**
- **Future work:**
 - **Automating the registration and fusion processes**